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Regular paper

Analyzing the effect of power loss allocation to utilities optimally in power systems using constrained load flow



In present day power system operation and control needs modern methodologies for controlling the power flow in power lines. Usually power electronic based converters are used for diverting/controlling the power flow through power lines which is a costlier solution. The alternative solution to this problem is to impose constraints on the system variables. In this paper, shunt capacitors are connected at loadsfor maintaining the desired magnitude at loads. Also, the losses thus obtained are allocated to respective participants (generators/loads) based on their contributions using tracing based methodology. In this, the proportional sharing principal is used to identify the contribution of participants in the power losses. The effect of imposing constraints on loss allocation to participants is analyzed at OPF (OPF) condition. For solving this, a new methodology based on improved ant lion optimization algorithm is developed. Using this method, the OPF problem wasansweredagainst system limitations. The developed methodologies are tested on standard IEEE-14 bus with supportivenumerary.

Keywords:Power flow tracing; Loss balancing procedure; Constrained load flow;Optimal power flow;Cost allocation.

Notation

- NC Number of shunt capacitors
- NL Number of loads
- NG Number of generators
- nl Number of transmission lines
- NT Number of tap changing transformers
- TPL Total power losses
- OPF Optimal Power Flow
- LCF Loss contribution factor

1. Introduction

The best electrical power flow is issue of power system. The optimum organization process of the practical power system leads to accurate and comfortable operation to the participants. The allocation of transmission price, transmission loss to the participants must do without affecting the other parameters. The participants in the power system are alternators and real power customers. One of the major issues in deregulated power system is the cost of power grid activity. The price control of the power system leads to increase the investment ability of the power grid. For this price flow procedure is done by taking the 'optimization decision making model [1].

In competitive power industrial market, the competition is existing among the participants of power system. This will give optimum and competitive electric pricing mechanism as 'retail' and 'wholesale'. The consumer satisfying component of the power

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system allow bids and submit the same to the 'wholesale' market and also to 'retail' market to rise the profit of authorities [2]. The main objective of power system operation is to increase the customer's satisfaction. 'The constrained nonlinear program' is the paradigm which creates the function with constraints. This function receives the information of power consumption of the customer which is classified into affordable, non-affordable and detachable consumers. The non-affordable consumers are same for all participants. Hence it is required to concentrate on affordable and detachable consumers for objective function [3].

The 'game theory' is one of the optimization algorithms. This algorithm is based on the market status. This is two level optimization approach which optimize generation and customer satisfaction [4]. The 'harmony search' algorithm is the phenomenon which is used for solving the ELD problem. It is self-indulgent process solution [5]. The economics consumption share is the procedure of assigning the load requirement and power generating source available. This problem is modelled as nonlinear dependent simplified issue [6]. The firefly algorithm is the procedure which gives the solution to the nonlinear inequality and nonlinear equality constraints optimization problem is presented in [7].

The optimal region is the major consideration in optimum electrical power flow issue. By using equality and inequality constraints, equivalent optimal region of optimal electrical power flow issue and set of continues stable equal states of a 'quotient gradient system' is derived. This will give optimum solution to allocate the losses in the power system [8]. The 'bio-inspired metaheuristic stud krill herd' procedure handles the best electrical load flow problem of power system. This method gives the optimum solution for the fairly loss allocation among the participants of the power system [9]. The proportional optimum electrical power flow procedures use linearized proportional AC load power flow problem so as to adjust the power flows. The electrical potential angles at the buses are taken as constraints for the objective function. After this, the losses are distributed to the participants to balance the power system [10].

The fractional level linear integral controller is used for solving the problem of optimum electrical power flow. The potential angle of the power system at various bus is not constant and not stable. By taking these two areas into consideration, the stability of the system is improved [11]. So as to combine the quick changes in power system and poor fast optimization calculations a new real time active power and reactive power optimum power flow' problem is solved by mixed integer linear paradigm [12].

After reviewing literature, the findings are that, many conventional methods are available for solving optimization problem. But, these methods fail for solving this problem while satisfying all inequality constraints. Hence, a new revolutionary algorithms based on swarm intelligence techniques have been developed to handle inequality constraints. It is also noticed that, increasing the number of constraints on optimization problem makes the algorithm to fail. Due to this, the recent trend concentrates in developing new hybrid optimization algorithms by taking the advantage of two or more algorithmic operations. In this paper, a new improved hybrid optimization methodology is explained for solving OPF problem by selecting generation fuel cost to be minimized against system limitations.

2. Mathematical formulation of constraints power flow

For any type of power system, maintaining voltage magnitude at load bus is a typical task and needs to alter the active and reactive power flows through transmission lines. This can be accomplished by injecting/absorbing reactive power from the buses for which voltage limits are to be maintained. In this work, the reactive power compensator is used to achieve this objective. The bus with the connection of capacitive compensation is shown in Fig.1.



Fig.1 Connection of capacitor at bus-k for compensation

The mathematical expression for the capacitor current injection $I_{cap,k}$ with susceptance $B_{cap,k}$ and voltage $V_{cap,k}$ is

$$I_{\text{cap},k} = jB_{\text{cap},k}V_{\text{cap},k}\forall \qquad k = 1,2,\dots,\text{NC}$$

Reactive power injected in to the system by the capacitor is expressed as

$$Q_{\text{cap,k}} = -V_{\text{cap,k}}^2 B_{\text{cap}} \quad \forall \quad k = 1,2,\dots,\text{NC}$$

Final expressions for active and reactive powers injected can be expressed as

$$P_{i} = \sum_{\substack{j=1\\j\neq k}}^{Nb} \left(V_{i}V_{j}Y_{ij}\cos(\theta_{ij} + \delta_{j} - \delta_{i}) \right) + \sum_{k=1}^{Ncap} \left(V_{i}V_{cap,k}Y_{ik}\cos(\theta_{ij} + \delta_{cap,k} - \delta_{i}) \right)$$
$$Q_{i} = -\sum_{\substack{j=1\\j\neq k}}^{Nb} \left(V_{i}V_{j}Y_{ij}\sin(\theta_{ij} + \delta_{j} - \delta_{i}) \right) - \sum_{k=1}^{Ncap} \left(V_{i}V_{cap,k}Y_{ik}\sin(\theta_{ij} + \delta_{cap,k} - \delta_{i}) \right)$$

After evaluating power injections, the respective power mismatch equations and Jacobian elements are calculated using procedure given in [12].

3. OPF Problem formulation

Conventionally, OPF problem with 'O_{fun}' as an objective function can be expressed as

Min $O_{\text{fun}}(x,u)$ Subjected to g(x,u) = 0; $h(x,u) \le 0$

Where, 'g' represents equality constraints and 'h' represents inequality constraints. 'x' represents a vector of state variables or called as dependent variables or also called as non-self restricted variables. 'u' represents a vector of control variables or called as independent variables or also called as self restricted variables. The details of these vectors can be expressed as

$$x^{T} = [P_{G_{1}}, V_{L_{1}}, V_{L_{2}}, \dots, V_{L_{NL}}, Q_{G_{1}}, Q_{G_{2}}, \dots, Q_{G_{NG}}, S_{l_{1}}, S_{l_{2}}, \dots, S_{l_{nl}}]$$
$$u^{T} = [P_{G_{2}}, P_{G_{3}}, \dots, P_{G_{NG}}, V_{G_{1}}, V_{G_{2}}, \dots, V_{G_{NG}}, Q_{sh_{1}}, Q_{sh_{2}}, \dots, Q_{sh_{NC}}, T_{1}, T_{2}, \dots, T_{NT}]$$

The control variables are generated through optimization algorithm in such a way that, the state variables are within their operational limits.

3.1 Equality constraints

The power balance equations in a system.

$$\sum_{i=1}^{NG} P_{G_i} - P_D - \sum_{i=1}^{Nbus} \sum_{j=1}^{Nbus} |V_i| |V_j| |Y_{ij}| \cos(\theta_{ij} + \delta_j - \delta_i) = 0$$
$$\sum_{i=1}^{NG} Q_{G_i} - Q_D + \sum_{i=1}^{Nbus} \sum_{j=1}^{Nbus} |V_i| |V_j| |Y_{ij}| \sin(\theta_{ij} + \delta_j - \delta_i) = 0$$

3.2 In-equality constraints

These are the constraints imposed on generator control variables, shunt capacitors, tap changing transformers and load buses, etc. These constraints can be mathematically expressed as

Self restricted in-equality constraints

Voltage magnitude limits: $V_{G_i}^{\min} \le V_{G_i} \le V_{G_i}^{\max}$; $\forall i \in NG$ Power generation (active power) limits: $P_{G_i}^{\min} \le P_{G_i} \le P_{G_i}^{\max}$; $\forall i \in 2,3,...NG$ Tap changing transformer limits: $T_i^{\min} \le T_i \le T_i^{\max}$; $\forall i \in NT$ Reactive power (capacitors) limits: $Q_{\text{sh}_i}^{\min} \le Q_{\text{sh}_i} \le Q_{\text{sh}_i}^{\max}$; $\forall i \in NC$

Non self restricted in-equality constraints

Power generation (slack bus) limits: $P_{G_i}^{\min} \leq P_{G_i} \leq P_{G_i}^{\max}$; $\forall i \in 1$ Power generation (reactive power) limits: $P_{G_i}^{\min} \leq Q_{G_i} \leq Q_{G_i}^{\max}$; $\forall i \in NG$ Power flow limit (apparent power) limits: $S_{l_i} \leq S_{l_i}^{\max}$; $\forall i \in nl$ Voltage magnitude (load bus) limits: $V_{L_i}^{\min} \leq V_{L_i} \leq V_{L_i}^{\max}$; $\forall i \in NL$

The self restricted in-equality constraints are fixed within its limits forcibly. Whereas the non self restricted in-equality constraints are handled using penalty approach [13]. The augmented objective function which includes non self restricted in-equality constraints can be expressed as

$$O_{\text{fun}}^{\text{Aug}}(\mathbf{x},\mathbf{u}) = O_{\text{fun}}(\mathbf{x},\mathbf{u}) + \lambda_p \left(P_{G_1} - P_{G_1}^{\text{limit}}\right)^2 + \lambda_q \sum_{i=1}^{N_G} \left(Q_{G_i} - Q_{G_i}^{\text{limit}}\right)^2 + \lambda_v \sum_{i=1}^{N_L} \left(V_{L_i} - V_{L_i}^{\text{limit}}\right)^2 + \lambda_s \sum_{i=1}^{n_I} \left(S_{l_i} - S_{l_i}^{\text{max}}\right)^2$$

Where, λp , λq , λv and λs are the coefficients related to slack bus active power generation, PV bus reactive power generation, load bus voltage and transmission line power flow limits. In the above equation, the limit values can be expressed as

how minuts. In the above equation, the limit values can be expressed as for slack bus active power generation $P_{G_1}^{\lim} = \begin{cases} P_{G_1}; if P_{G_1}^{\min} \leq P_{G_1} \leq P_{G_1}^{\max} \\ P_{G_1}^{\min}; if P_{G_1} \geq P_{G_1}^{\min} \\ P_{G_1}^{\min}; if P_{G_1} \leq P_{G_1}^{\min} \end{cases}$ for PV bus reactive power generation $Q_G^{\lim} = \begin{cases} Q_G; if Q_G^{\min} \leq Q_G \leq Q_G^{\max} \\ Q_G^{\min}; if Q_G \geq Q_G^{\max} \\ Q_G^{\min}; if Q_G \leq Q_G^{\min} \\ Q_G^{\min}; if V_L \geq V_L^{\max} \\ V_L^{\min}; if V_L \geq V_L^{\max} \\ V_L^{\min}; if V_L \leq V_L^{\min} \\ V_L^{\min}; if V_L \leq V_L^{\min} \\ S_l^{\min}; if S_l \geq S_l^{\max} \end{cases}$ 3.3 Total cost function

3.3 Total cost function

Total cost objective formulated using costs related to TPL and shunt capacitors cost. The equation used to this cost function is given as

 $O_{\text{COST}}(\mathbf{x},\mathbf{u}) = \sum_{i=1}^{NG} \text{FC}_i(P_{G_i}) + \text{COST}_{\text{TOTAL}} \$/\text{hr}$ (1) Here, the total cost of ith generating unit fuel can be expressed as $FC_i(P_{G_i}) = a_i P_{G_i}^3 + b_i P_{G_i}^2 + c_i P_{G_i} + d_i \$/\text{hr}$ Similarly, the total cost can be given as $COST_{\text{TOTAL}} = COST_{\text{TPL}} + COST_{\text{CAPACITOR}} \$/\text{hr}$ (2)

3.3.1 TPL cost

The mathematical expression used to calculate TPL in a given system is given as

$$TPL = \sum_{i=1}^{m} \left(g_i \left[|V_i|^2 + |V_j|^2 - 2|V_i| |V_j| \cos(\delta_i - \delta_j) \right] \right) MW$$

After this, the cost of total power losses with ' λ_{TPL} ' cost factor with a value 5 \$/MWhr clearing price can be calculated as [14]

$$\text{COST}_{\text{TPL}} = \sum_{i=1}^{\text{nl}} \left(\frac{|\text{Pflow}_i| \times \lambda_{\text{TPL}}}{f_{\text{mn}}^i} \right) \frac{1}{h^i}$$

Here, 'P_{flow,i}' is the active power flow in ith line and ' f_{mn}^{i} ' is a factor of ith line connected between buses m and n, which can be calculated using

$$f_{\rm mn}^i = \frac{\delta_m - \delta_n}{X(i)}$$

Here, X(i) is the reactance of ith line.

3.3.2 Capacitor's reactive power compensation cost

The expression used to calculate cost of capacitor's reactive power compensation is considered with the ratio of costs related to investment and operational is 0.03652 \$/MVArhfrom [15, 16] and is given as

 $COST_{CAPACITOR} = \frac{Investment \ cost}{Operating \ cost} \times Capacitor(s) \ reactive \ power \ value \qquad $/hr$ The modified equation is given as

 $COST_{CAPACITOR} = 0.03652 \times Q_{sh}$

4. TPLsharingprocedure

In order to share losses to generating units, the economic load dispatch (ELD) problem is solved at first. Then after, the active power generated from generating units is evaluated using procedure given in [17], the expression given below is used to calculate power generated from unit-i.

$$P_{G_i} = \left| \frac{-b_i + \sqrt{b_i^2 - 3a_i(c_i - \lambda)}}{3a_i} \right| \tag{3}$$

Upon simplification,

$$P_{\rm Gi} = \frac{-b_i}{3a_i} + \sqrt{\left(\frac{b_i}{3a_i}\right)^2 - \frac{(c_i - \lambda)}{(3a_i)}} \\ P_{\rm Gi} = \frac{-b_i}{3a_i} + \frac{b_i}{3a_i} \sqrt{1 - \frac{(c_i - \lambda)}{(3a_i)} \left(\frac{3a_i}{b_i}\right)^2} \\ P_{\rm Gi} = \frac{-b_i}{3a_i} + \frac{b_i}{3a_i} \left(1 - \frac{(c_i - \lambda)}{(3a_i)} \left(\frac{3a_i}{b_i}\right)^2\right)^{\frac{1}{2}}$$
(4)

Binomial series expansion is considered for simplification,

$$P_{\rm Gi} = \frac{\lambda - c_i}{2b_i} \tag{5}$$

Upon simplification, the value of ' λ ' can be given as

$$\lambda = \frac{\frac{\sum_{j=1}^{NG} P_{Gj} + \sum_{j=1}^{NG} \frac{D_j}{3a_j}}{\sum_{j=1}^{NG} \frac{1}{3a_j} - \sum_{j=1}^{NG} b_j + \sum_{j=1}^{NG} \frac{3a_j c_j}{2b_j}}{\sum_{j=1}^{NG} 3a_j}$$
(6)

Using above equations, the final equation obtained to calculate new value for

generation from unit-i can be given as

$$P_{\text{Ginew}} = \frac{\frac{\sum_{j=1}^{\text{NG}} P_{\text{Gj}} + \sum_{j=1}^{\text{MG}} \frac{D_j}{3a_j}}{\sum_{j=1}^{\text{NG}} \frac{1}{3a_j}} - \sum_{j=1}^{\text{NG}} \frac{b_j + \sum_{j=1}^{\text{NG}} \frac{3a_jc_j}{2b_j}}{2b_j}}{2b_j}$$
(7)

Upon simplification, the final expression for active power generation

$$P_{\text{Ginew}} = \left[\frac{P_{\text{Gi}_{\text{sch}}}}{2b_{i} \left(\sum_{j=1}^{NG} 3a_{j}\right) \left(\sum_{j=1}^{S} \frac{1}{3a_{j}}\right)} + \frac{\sum_{j=1}^{NG} \frac{b_{j}}{3a_{j}}}{2b_{i} \left(\sum_{j=1}^{NG} 3a_{j}\right) \left(\sum_{j=1}^{NG} \frac{1}{3a_{j}}\right)} - \frac{\sum_{j=1}^{NG} \frac{b_{j}}{2b_{j}}}{2b_{i} \sum_{j=1}^{NG} 2b_{j}} - \frac{c_{i}}{2b_{i}}\right] + (\text{LCF}_{i} \times P_{L})$$
Here, the equation for LCF can be given as $\text{LCF}_{i} = \frac{1}{2b_{i} \left(\sum_{j=1}^{NG} 3a_{j}\right) \left(\sum_{j=1}^{NG} 3a_{j}\right)}$
(8)

5. Improved Antlion Optimization Algorithm (IALO)

This algorithm is in spired from the hunting behavior of antlions [18]. Every optimization algorithm starts with the random generation of control variables within the respective minimum and maximum boundaries for a given 'N' number of populations. In this problem, the control problems are self restricted inequality constraints explained in section 3.2. The step by step methology to be followed is respresented in the following flowchart shown in Fig.222.



Fig.2 Flowchart of the improved antlion optimization algorithm

7. Results and Analysis

To analyze the effect of OPF on loss and loss cost allocation methodologies, the developed methodology is tested on IEEE-14 bus test system [23]. The entire analysis is performed for the following Modules.

Module-1: Analyzing the effect of combining loss cost with the generation cost in conventional load flow.

To identify the effect of selecting loss cost in addition to generation fuel cost in Module-1, OPF problem is solved separately for the three costs.

- i. Generation fuel cost $(\sum_{i=1}^{NG} FC_i(P_{G_i}))$
- ii. Sum of power loss cost and compensators cost $(COST_{TPL} + COST_{CAPACITOR})$
- iii. Total cost objective $(O_{COST}(x,u))$

Module-2: Analyzing the effect of combining loss cost with the generation cost in constrained load flow.

Module-3: Allocating power losses to generators using balancing procedure.

In Module-1, the OPF results for the three different cost objectives are tabulated in Table.1. From this table, it is observed that, the cost objective value is decreased with proposed IALO method when compared to existing ALO method. It is also noticed that, while minimizing generation cost objective, the cost pertaining to total power losses is increased and vice-versa. Hence, the total cost objective function is formulated and is minimized while satisfying system equality and inequality constraints. The results obtained with total cost objective are compromised results with both generation cost and loss cost objectives. It is observed that, the time taken for convergence is decreased with proposed IALO when compared with ALO irrespective of the cost objective. The convergence characteristics of three cost objectives are shown in Fig.4. From these figures, it is identified that, due to the effectiveness of the proposed method, the iterative process starts with good initial value and converges to final best value in less number of iterations when compared to existing method.

		Gene	ration	Lo	sses	Total o	cost		
Paramet	ers	Existing ALO	Proposed IALO	Existing ALO	Proposed IALO	Existing ALO	Propos ed IALO		
	PG1	35.2766	36.51058	10.71735	29.67454	33.57665	18.045 3		
Active power	PG2	92.03853	87.97381	130.7939	96.23036	117.3704	106.89 6		
generations (MW)	PG3	60	60	60	60	46.59449	60		
(14144)	PG6	49.08658	50	42.77829	49.46524	39.78489	50		
	PG8	25.00054	26.723	17.35166	26.29561	25.1086	26.329 13		
	VG1	1.096046	1.1	1.1	0.998875	1.002215	1.1		
Concretor	VG2	0.956629	0.97664	0.991703	0.921178	0.924751	0.9		
voltage	VG3	0.989146	0.939744	0.9	0.9668	0.968049	0.9671 98		
(p.u.)	VG6	1.010136	1.1	1.091719	0.987745	0.965168	1.0400 72		
	VG8	1.022868	1.1	1.082621	0.997982	0.969008	1.0544 37		
Tap changing	TAP 4- 7	1.086569	0.992494	1.019094	0.995313	1.044813	1.0385 84		
transformer settings,	TAP 4-9	1.0704	1.010329	1.017971	0.956667	1.030385	1.0504 59		
(p.u.)	TAP,5- 6	1.054269	0.967281	0.973671	0.983193	0.994583	1.0300 88		
Reactive power of shunt capacitor,	QC9	30	30	30	30	29.05232	30		

 Table.1 OPF results for three cost objectives with conventional load flow using existing and proposed methods of IEEE-14 bus system

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						-
(MVAr)						
Total active power generation, MW	261.4023	261.2074	261.6412	261.6657	262.4351	261.27 05
Total generation fuel cost, \$/hr	7728.557	7720.724	7816.409	7737.807	7785.342	7755.9 37
Total active power losses, MW	2.40225	2.20738	2.64119	2.665738	3.435059	2.2704 68
Total power loss cost, \$/hr	221.8569	230.7002	202.8787	181.0995	191.3279	212.92 41
Voltage deviation (Vdev), p.u	0.58689	0.559884	0.670301	0.542116	0.711618	0.4981 82
Time, Sec	35.1789	31.0021	28.8273	26.1762	49.2881	43.928







Further, the OPF result of generation cost objective with the proposed IALO method is validated with the existing methods given in Table.2. From this table, it is identified that, the generation fuel cost objective value is decreased with proposed method when compared to existing methods listed in the literature.

Table.2 V	alidation of OPF res	ilts for generation cost objective	of IEEE-14 bus system

Methods		Total generation fuel cost, \$/hr	Time, Sec
Existing	GA [24]	18611.07	-
	PPSO [24]	18610.40	-
	ALO	7728.557	35.1789
Proposed IALO		7720.724	31.0021

Further, in Module-2, the OPF results with conventional and constrained load flow methods for the three different cost objectives are tabulated in Table.3. From this table, it is observed that, with constrained load flow, the value of cost objectives related generations, losses and total costs is increased when compared to conventional load flow method. Similarly, the time taken for convergence is also increased with constrained load flow when compared to conventional load flow method. It is also observed that, the total generation and there by the total power losses are increased with constrained load flow method. The convergence characteristics with proposed IALO method using conventional and constrained load flows methods are shown in Fig.5. From this figure, it is observed that, due to imposition of voltage constraint with constrained load flow, the iterative process starts with highest initial value and reaches final best value in more number of iterations when compared to conventional load flow method.

The variation of generations with three cost objectives using conventional and constrained load flows is shown in Fig.6. From this figure, it is noticed that, there is a significant variation of generations connected at buses 1 and 2 so as to minimize the respective cost objectives.

Parameters		OPF results with cost objective related to (\$/hr)							
		Conv	entional res	ults	Constrained results				
		Generation	Losses	Total cost	Generation	Losses	Total cost		
	PG1	36.51058	29.67454	18.0453	21.51601	12.9161	49.29146		
Active power	PG2	87.97381	96.23036	106.896	107.0802	117.2719	113.5223		
generations	PG3	60	60	60	60	58.0344	49.47036		
(MW)	PG6	50	49.46524	50	50	49.70681	36.5905		
	PG8	26.723	26.29561	26.32913	23.14529	23.80739	13.75687		
	VG1	1.1	0.998875	1.1	1.079982	1.088378	1.086362		
	VG2	0.97664	0.921178	0.9	0.9	0.932507	0.924385		
Generator voltage magnitudes, (p.u.)	VG3	0.939744	0.9668	0.967198	0.948917	0.995988	0.974697		
g, (_F)	VG6	1.1	0.987745	1.040072	0.992585	0.993127	0.996091		
	VG8	1.1	0.997982	1.054437	1.037065	1.031871	1.034422		
Tan changing	TAP,4-7	0.992494	0.995313	1.038584	1.032817	1.053598	1.043845		
transformer	TAP,4-9	1.010329	0.956667	1.050459	1.001049	0.998067	1.015606		
settings, (p.u.)	TAP,5-6	0.967281	0.983193	1.030088	1.095757	1.1	1.082125		
Reactive power of shunt capacitor, (MVAr)	QC9	30	30	30	30	30	30		
Total active power g MW	eneration,	261.2074	261.6657	261.2705	261.7415	261.7366	262.6315		
Total generation fuel cost, \$/hr		7720.724	7737.807	7755.937	7759.377	7782.068	7779.104		
Total active power losses, MW		2.20738	2.665738	2.270468	2.741492	2.736637	3.631509		
Total power loss cost, \$/hr		230.7002	181.0995	212.9241	230.3082	192.6807	193.8231		
Voltage deviation (V	/dev), p.u	0.559884	0.542116	0.498182	0.602343	0.577016	0.955624		
Time, Sec		31.0021	26.1762	43.9283	39.0012	28.3478	53.2911		

Table.3 OPF results for three cost objectives with conventional and constrained load flow
methods of IEEE-14 bus system

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Fig.5 Convergence characteristics of OPF with IALO using conventional and constrained load flows of IEEE-14 bus system



Fig.6 Variation of generations with three OPF cost objectives using conventional and constrained load flows of IEEE-14 bus system

In this Module, the comparative results with load flow and OPF problems are tabulated in Table.4. From this table, it is observed that, with OPF, the total generation and there by the total power losses is decreased when compared to load flow. It is also observed that, with OPF, the value of generation fuel cost objective is increased due to imposition of inequality constraints when compared to load flow. Variation of generations in load flow and OPF methods with conventional and constrained load flows is shown in Fig.7. From this figure, it is observed that, due to satisfy inequality constraints in OPF, the generator connected at bus-1 is decreasing its generation and whereas the generators connected at buses 2 and 3 are increasing its generation when compared to load flow.

IEEE-14 bus system								
Parameters	Conventional results with				Constrained results with			
	Load flow		OPF		Load flow		OPF	
	Gen	Cost	Gen	Cost	Gen	Cost	Gen	Cost
	(MW)	(\$/hr)	(MW)	(\$/hr)	(MW)	(\$/hr)	(MW)	(\$/hr)

Table.4 Comparative results of load flow and OPF problems for cost objective of IEEE-14 bus system

	PG	85.568	1351.4	18.045	875.28	86.185	1355.8	49.291	1094.4
	1	61	19	3	08	31	09	46	93
A	PG	27.766	1720.5	106.89	2360.1	27.766	1720.5	113.52	2421.0
Active	2	3	73	6	67	3	73	23	43
power	PG	39.687	1565.9	60	1710.6	39.687	1565.9	49.470	1635.5
generatio	3	45	59	00	56	45	59	36	72
ns (MW)	PG	81.889	1325.2	50	1099.4	81.889	1325.2	36.590	1005.1
	6	98	46	50	86	98	46	5	56
	PG	27.766	1720.5	26.329	1710.3	27.766	1720.5	13.756	1622.8
	8	3	73	13	47	3	73	87	4
Total act	ive								
power		262.67		261.27		263.29		262.63	
generatio	on,	86	-	05		53	-	15	
MW									
Total			7683 7		7755.0		7688 1		7770 1
generation	fuel	-	7085.7	-	37	-	61	-	04
cost, \$/]	hr		/1		57		01		04
Total act	ive	3 6786		2 2704		4 2953		3 6315	
power los	ses,	33	-	68	-	30	-	09	-
MW		55		00		37		07	
Qsh, MV	'Ar	19	-	30	-	19	-	30	-





Voltage magnitudes obtained with load flow and OPF problems are tabulated in Table.5. From this table, it is identified that, due to imposition of voltage magnitude constraints in OPF, the voltage magnitudes at buses are maintained nearly at 1.0 p.u when compared to load flow. Variation of voltage magnitudes in load flow and OPF problems with conventional and constrained load flows is shown in Figs.8 and 9.

Table.5 Voltage magnitudes obtained with OPF after balancing power losses to generators

of IEEE-14 b	us systen
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Bus No		Voltage mag	gnitude, p.u.		
	Convention	nal results	Constrained results		
	Load flow	OPF	Load flow	OPF	



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Similarly, power flows obtained with load flow and OPF problems are tabulated in Table.6. From this table, it is identified that, due to imposition of line flow thermal constraints in OPF, the power flow in lines are maintained below the rated MVA limit when compared to load flow.

ILLE 14 bus system								
T in a	Power flow, MVA							
Line No	Convention	nal results	Constrain					
	Load flow	OPF	Load flow	OPF	Limit			
01	58.86035	39.99843	58.8137	35.369	150			
02	23.75018	24.86626	23.95568	32.01929	85			
03	34.97252	32.47181	34.78535	40.74617	85			
04	20.31584	31.71575	20.35061	39.87376	85			
05	10.02681	24.68357	10.3918	31.43853	85			
06	19.2086	5.759455	18.38614	8.242197	85			
07	43.8671	30.59421	42.71899	36.43101	150			
08	6.650658	10.75119	5.536416	12.66635	30			
09	3.562349	9.262137	5.712273	11.58283	32			
10	25.65331	26.46907	24.21849	25.54518	45			
11	19.29802	13.11217	25.33717	21.09559	14			

Table.6 Power flows obtained with OPF after balancing power losses to generators of

IEEE-14 bus system

12	9.41871	8.780948	10.10396	9.743732	32
13	24.486	21.67897	26.57311	24.95387	22
14	31.92323	27.38311	34.72648	26.7003	32
15	25.41541	28.81145	29.64147	34.20549	29
16	10.78	5.759801	15.26214	11.84503	32
17	6.975795	7.61065	12.31609	17.48794	18
18	15.57537	9.171989	17.46827	10.47438	12
19	3.047364	2.34193	3.645822	3.51447	12
20	13.07425	9.130183	14.78863	13.65302	12

In Module-3, OPF results before and after balancing total power losses are tabulated in Table.7. From this table, it is identified that, in conventional load flow, the total generation and its fuel cost and thereby the total power losses are increase dafter balancing total power losses. It is also observed that, the generations are modified after balancing power losses accordingly as their contributions. But, in OPF results with constrained load flow problem, the total generation, its cost and power losses are increased when compared to OPF results with conventional load flow problem even after balancing total power losses. From the results, it is also identified that, with constrained load flow, the generators connected at buses 1 and 2 are increasing its generation and where as generators connected at buses 3, 6 and 8 are decreasing its generation. Variation of generators generation before and after balancing losses in OPF with conventional and constrained load flows is shown in Fig.10.

Parameters		Conventional results				Constrained results			
		Before balancing		After balancing		Before balancing		After balancing	
		Gen (MW)	Cost (\$/hr)	Gen (MW)	Cost (\$/hr)	Gen (MW)	Cost (\$/hr)	Gen (MW)	Cost (\$/hr)
Active power generatio ns (MW)	PG1	18.04 53	875.28 08	17.202 26	869.39 28	49.291 46	1094.4 93	47.927 3	1084.8 82
	PG2	106.8 96	2360.1 67	106.95 64	2360.7 16	113.52 23	2421.0 43	113.61 89	2421.9 4
	PG3	60	1710.6 56	60.851 77	1716.7 37	49.470 36	1635.5 72	50.832 72	1645.2 77
	PG6	50	1099.4 86	50.648 95	1104.0 6	36.590 5	1005.1 56	37.628 46	1012.4 45
	PG8	26.32 913	1710.3 47	26.389 53	1710.7 76	13.756 87	1622.8 4	13.853 48	1623.5
Total active power generation, MW		261.2 705	-	262.04 89	-	262.63 15	-	263.86 09	-
Total generation fuel cost, \$/hr		-	7755.9 37	-	7761.6 82	-	7779.1 04	-	7788.0 44
Total active power losses, MW		2.270 468	-	3.0489 49	-	3.6315 09	-	4.8609	-
Total power loss cost, \$/hr		-	212.92 41	-	184.27 94	-	193.82 31	-	644.76 57
Qsh, MVAr		30	-	30	-	30	-	30	-
Voltage deviation (Vdev), p.u		0.498 182	-	0.5673 8	-	0.9556 24	-	0.9982 93	-

-		-
Table.7	OPF results with cost objectives before and after balancing powe	r losses of
	IEEE-14 bus system	



Fig.10 Variation of generators generation before and after balancing losses in OPF with conventional and constrained load flows of IEEE-14 bus system

9. Conclusions

In this paper, a new hybrid optimization algorithm namely improved ant-lion optimization algorithm has been developed. With this, the OPF problem has been solved by taking generation fuel cost as an objective while satisfying system equality and inequality constraints. From the results, it has been observed that, the proposed method has proven its effectiveness in solving OPF with constrained load flow problem along with system constraints. It has been also identified that, the developed method starts the iterative process with good initial value and reaches final best value in less number of iterations when compared to existing method. The losses thus obtained have been allocated to generators accordingly based on their contributions. The comparative results have been analyzed by comparing with load flow results.

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